

Data Structure and Algorithm Analysis

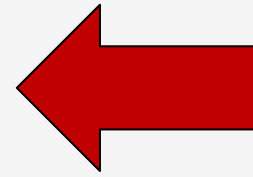
Chapter 11: Graph

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6. Shortest Path
7. Minimum Spanning Tree



**Study Four
common
problems
in graphs**

1. Graphs have wide, wide applications

- Modeling **relationships** (families, organizations)
 - e.g., Model **friendships** in social networks
- Modeling **connectivity** in computer networks
- Representing maps
 - E.g., google map
- Finding paths from start to goal
- ...
- Binary trees, B trees, B+ trees are **special** graphs

2. Notations in Graphs

■ Unweighted graph vs. weighted graph

■ Undirected graph vs. directed graph

**Graph
properties**

■ Degrees **← The importance of vertices in a graph**

■ Path and cycle

■ Path length

■ Connectivity

■ Connected components

■ Acyclic directed graph

**Relationship
between
vertices in a
graph**

Definition of an unweighted graph

- A graph $\mathbf{G} = (\mathbf{V}, \mathbf{E})$ consists of a set \mathbf{V} of **vertices**, and a set of **edges** \mathbf{E} , such that each edge in \mathbf{E} is a connection between a pair of vertices in \mathbf{V}

$$\square n=|V|, m=|E|$$

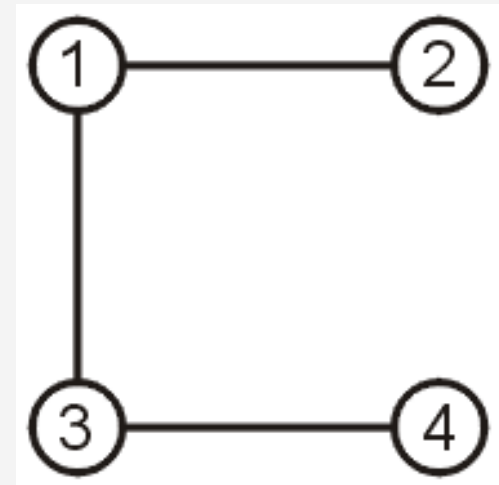
- Example: given the vertices

$$V = \{v_1, v_2, v_3, v_4\}$$

and the edges

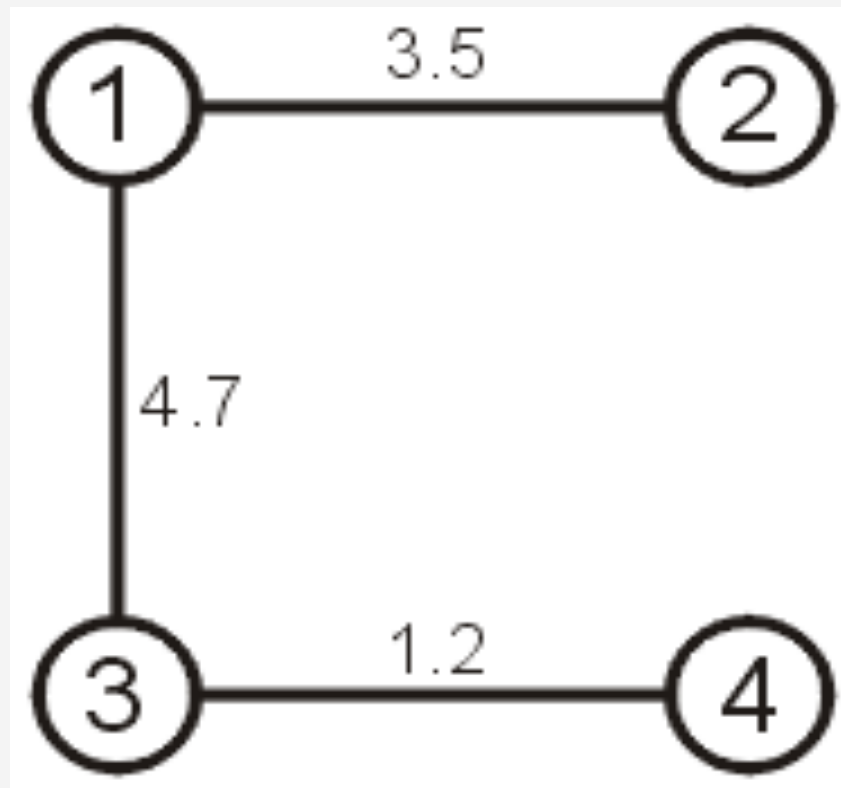
$$E = \{\{v_1, v_2\}, \{v_1, v_3\}, \{v_3, v_4\}\}$$

the graph has **three edges** connecting four vertices



Weighted Graphs

- Each **edge** may be associated with a **weight**
- This could represent **distance**, **time**, **energy consumption**, **cost**, etc

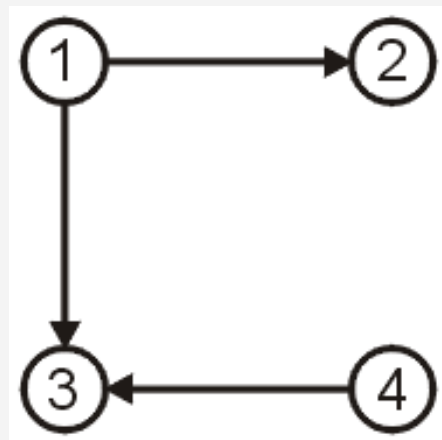


Directed Graphs

- **Each edge** in a graph may be associated with a **direction**
- An edge from v_i to v_j **does not imply** an edge from v_j to v_i
- All edges are ordered pairs (v_i, v_j) where this denotes a connection **from v_i to v_j**
- Such a graph is termed a **directed graph**
- For example,

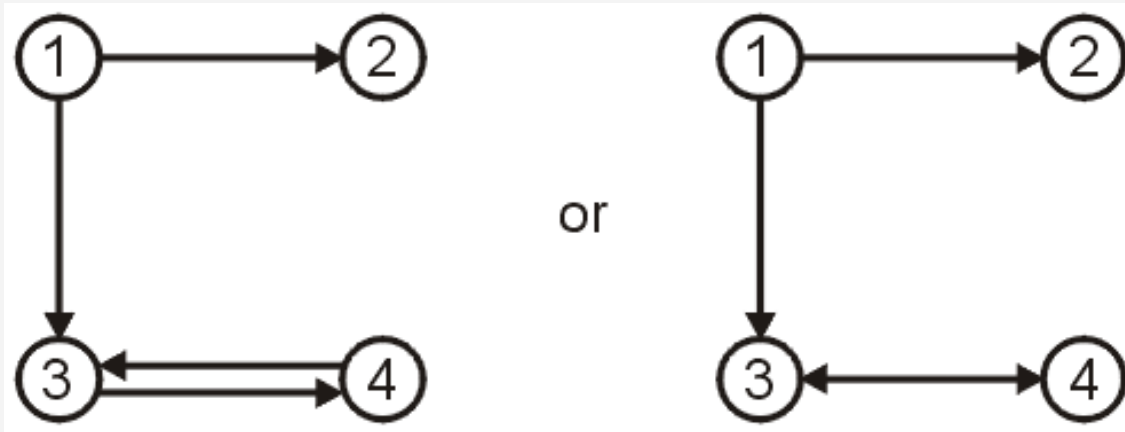
$$V = \{1, 2, 3, 4\}$$

$$E = \{(1, 2), (1, 3), (4, 3)\}$$



Directed Graphs

- If there is an edge from v_i to v_j and an edge from v_j to v_i , plotted as

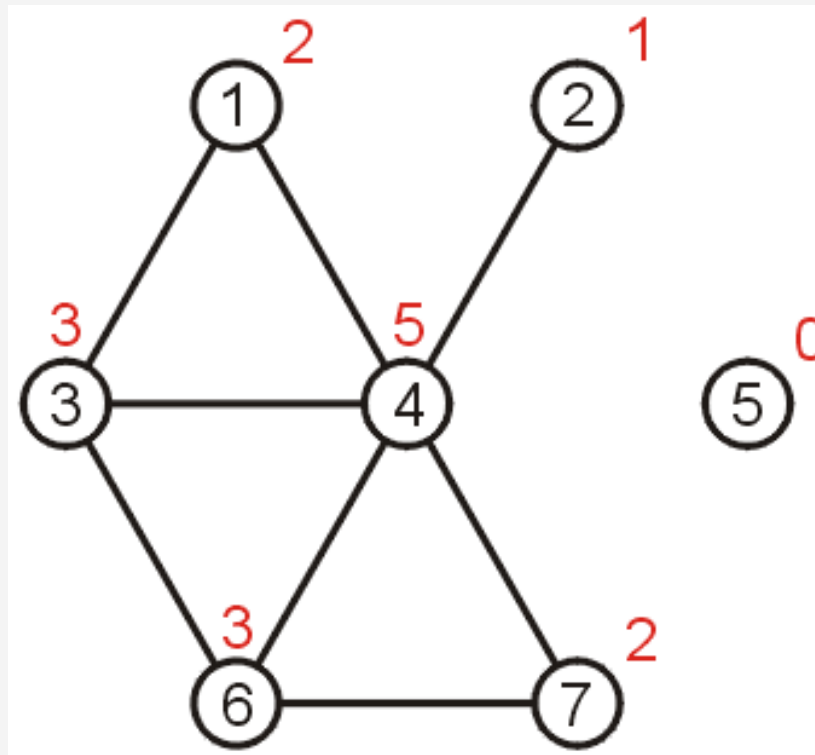


Directed Graphs vs. undirected graphs

- Graphs **without directions** are termed *undirected graphs*
- An **undirected** graph can be considered as a directed graph with **each edge** on **both directions**

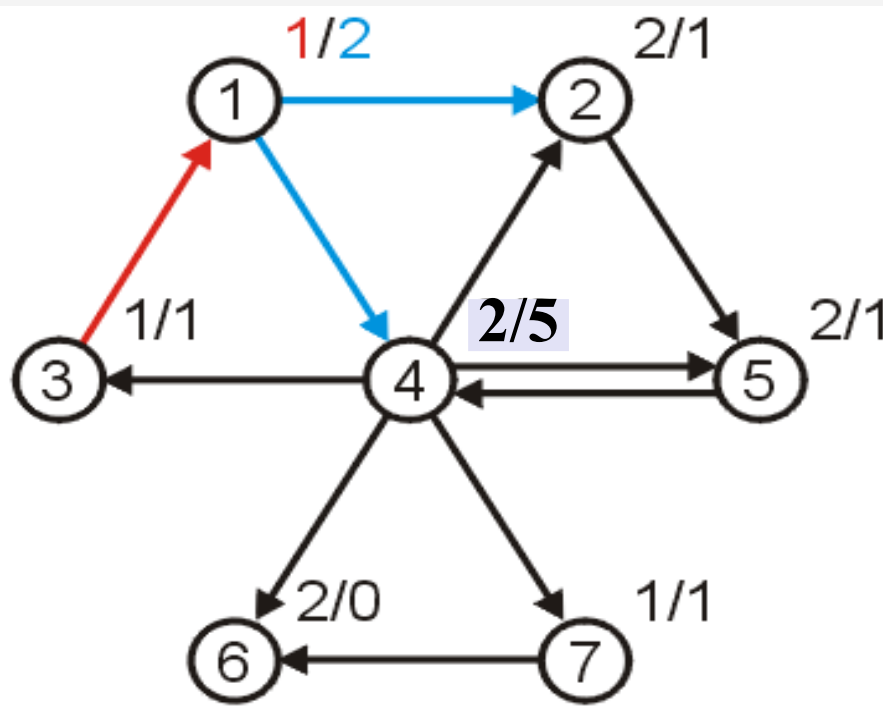
Degrees in an undirected graph

- We usually care how many neighbors of each vertex,
 - Especially the vertices with many neighbors
- The degree of a vertex is the number of neighbors



In and Out Degrees in a directed graph

- The **in (incoming) degree** of a vertex is the number of its **incoming** neighbors
- The **out (out-going) degree** of a vertex is the number of its **out-going** neighbors
- **in/out**



Paths

- A **path from v_0 to v_k** is an ordered sequence of vertices

$$(v_0, v_1, v_2, \dots, v_k)$$

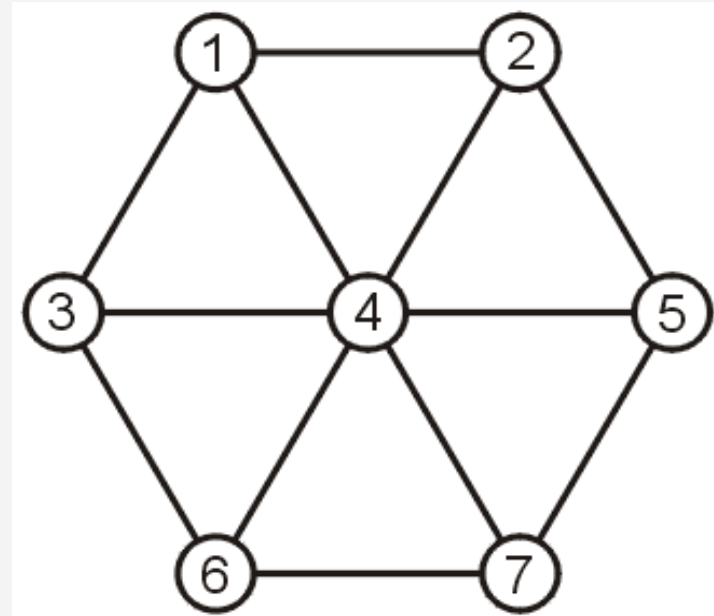
where $\{v_{i-1}, v_i\}$ is an **edge** for $i = 1, \dots, k$

- Examples of paths from **1 to 5**:

$$(1, 2, 5)$$

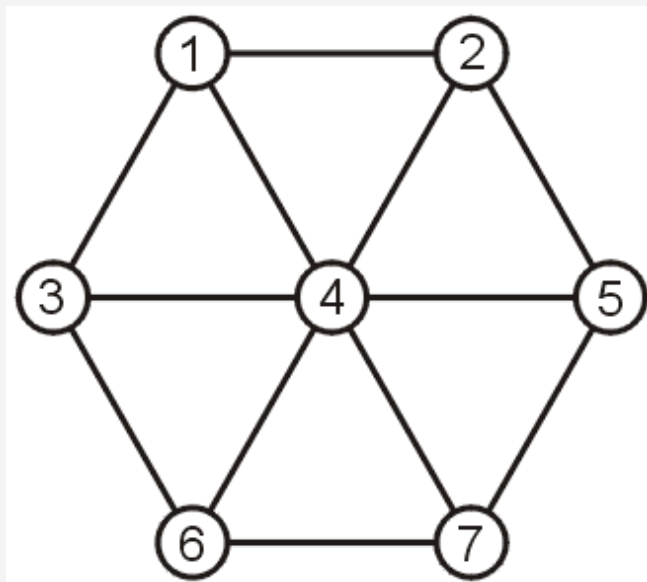
$$(1, 4, 7, 5)$$

$$(1, 2, 4, 1, 2, 5)$$



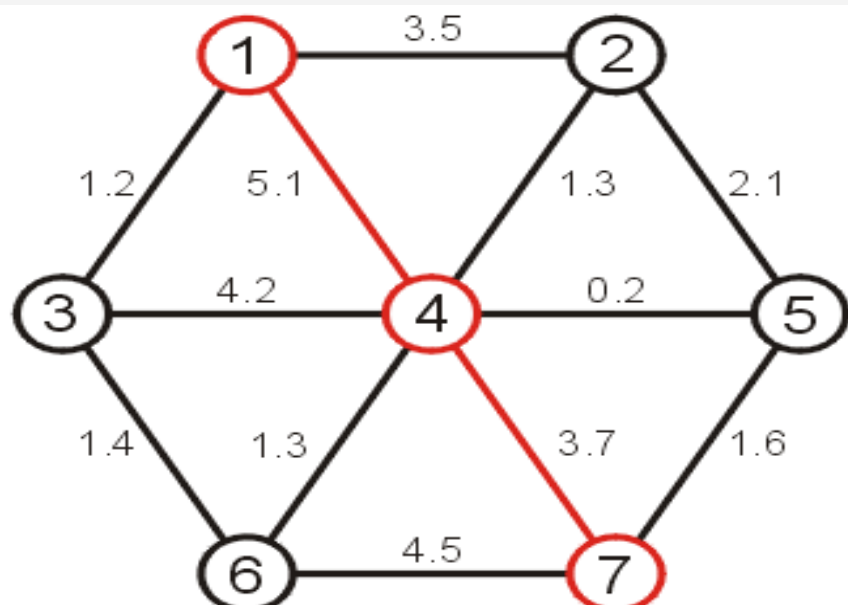
Simple Paths

- A *simple path* has **no repetitions** other than perhaps the first and last vertices
 - (1, 2, 5) **simple** path
 - (1, 2, 4, 1, 2, 5) **not** simple path
- A *simple path* where the **first and last vertices** are **equal** is said to be a *cycle*
 - e.g., (1, 2, 4, 1)



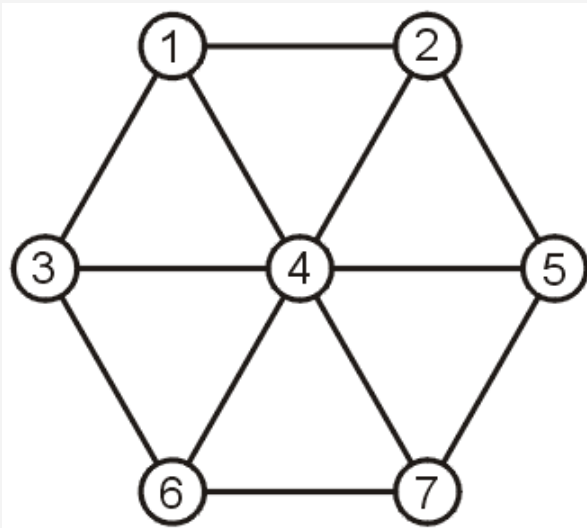
Path length

- The **length** of an **unweighted path** is the **number of edges** in the path
- The **length** of a **weighted path** is the **weighted sum of the edges** in the path
 - The length of the path $1 \rightarrow 4 \rightarrow 7$ in the following graph is $5.1 + 3.7 = 8.8$

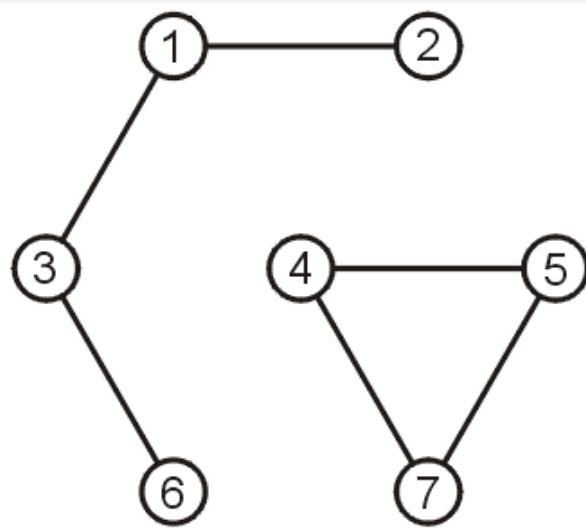


Connectivity

- Two vertices v_i, v_j are said to be *connected* if there is a *path* between v_i to v_j
- A *graph* is *connected* if there is a *path* between any two vertices



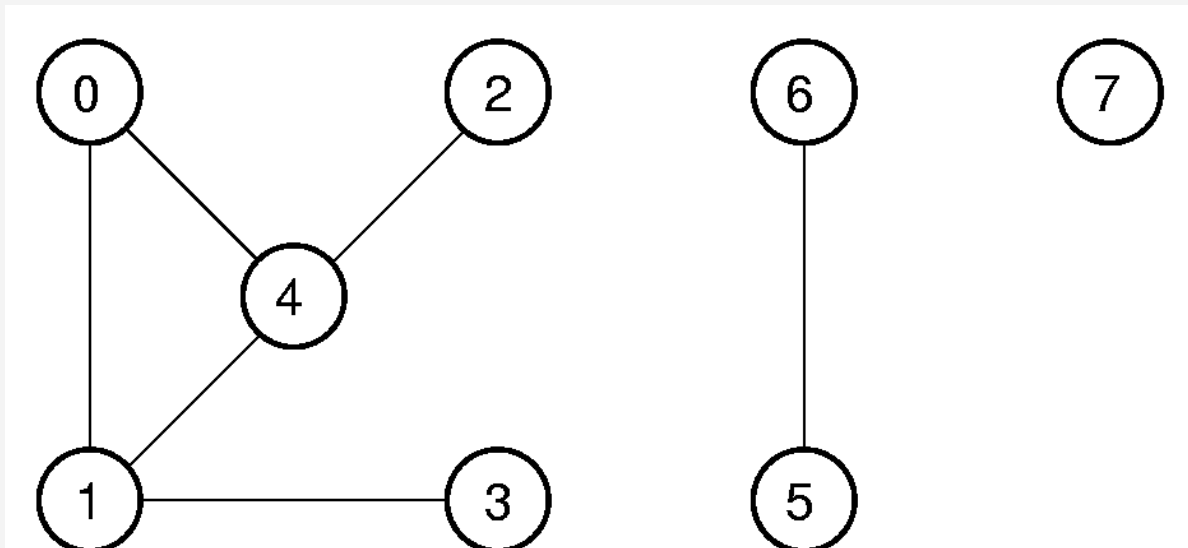
Connected graph



Disconnected graph

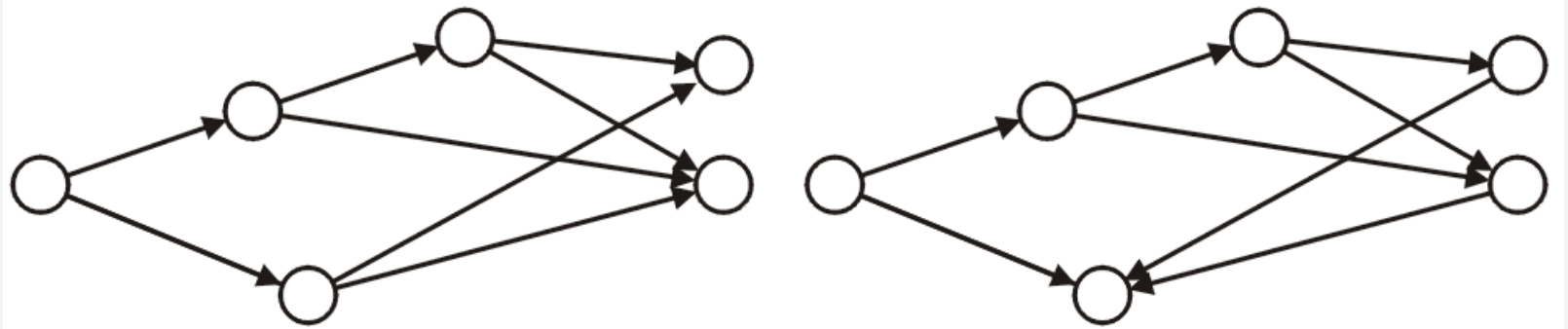
Connected Components

- A graph may be **disconnected**
- But a **subgraph** may be **connected**
- A **maximum connected subgraph** of a graph is called a **connected component (CC)**, e.g.,
 - CC1 with vertices 0, 1, 2, 3, 4
 - CC2 with vertices 5, and 6
 - CC3 with only vertex 7

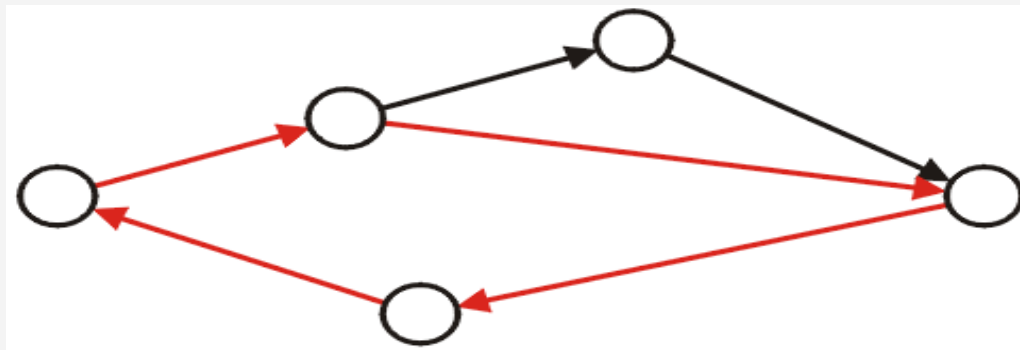


Directed Acyclic Graphs

- A *directed acyclic graph (DAG)* is a directed graph which has **no cycles**
- Two example DAGs



- Not a DAG



Applications of Directed Acyclic Graphs

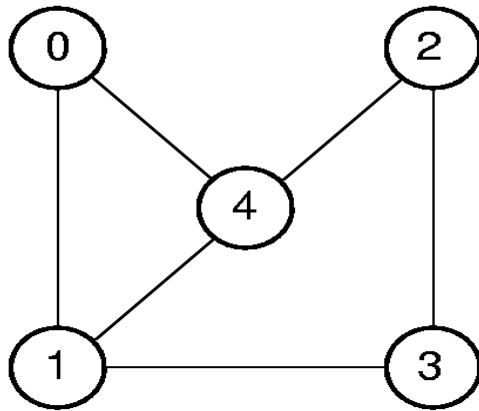
- Applications of DAGs include:
 - Family trees
 - Course pre-requisites
 - Folders and sub folders in an Operation system
 - ...

3. Representations of a graph in computers

- Adjacency Matrix
- Adjacency List

Representations for an Undirected graph

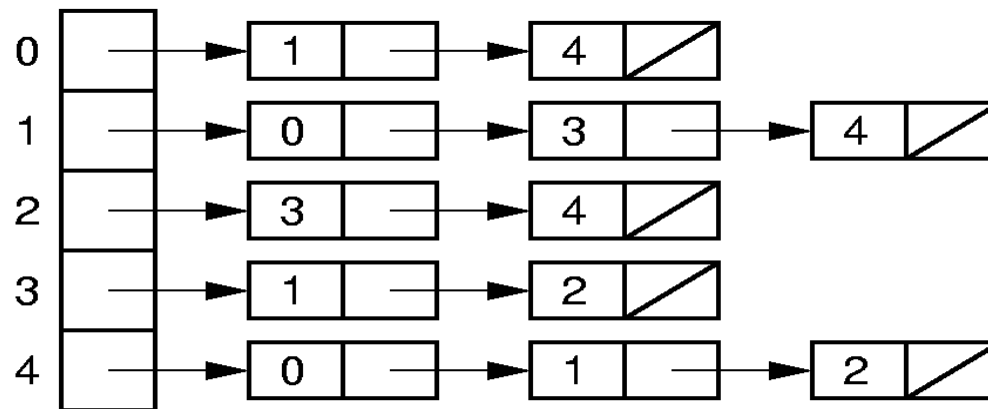
- a) Graph structure b) Adjacency matrix for the graph c) Adjacency list for the graph



(a)

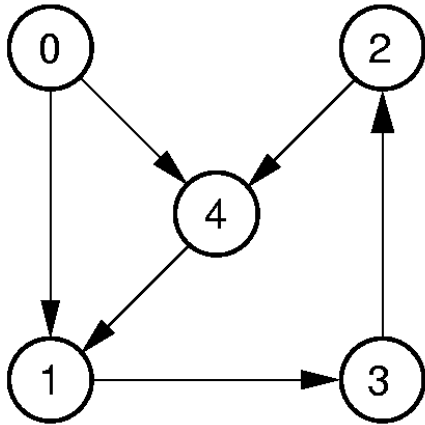
	0	1	2	3	4
0		1			1
1	1			1	1
2				1	1
3		1	1		
4	1	1	1		

(b)



(c)

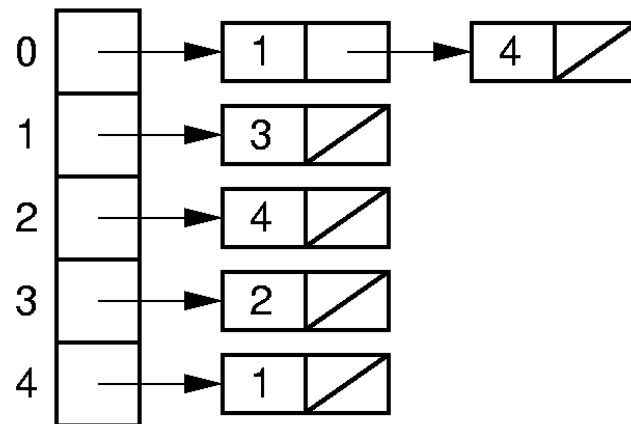
Representations for a directed graph



(a)

	0	1	2	3	4
0		1			1
1				1	
2					1
3			1		
4		1			

(b)



(c)

Representation **Space** costs

- Adjacency Matrix:
 - $\Theta(n^2)$
 - $n=|V|$ and $m=|E|$
 - Suitable for **dense** graphs
- Adjacency List
 - $\Theta(n+m)$
 - $m \leq n(n-1)$
 - Suitable for **sparse** graphs
 - Most **real graphs** are **sparse**

4. Graph Traversals

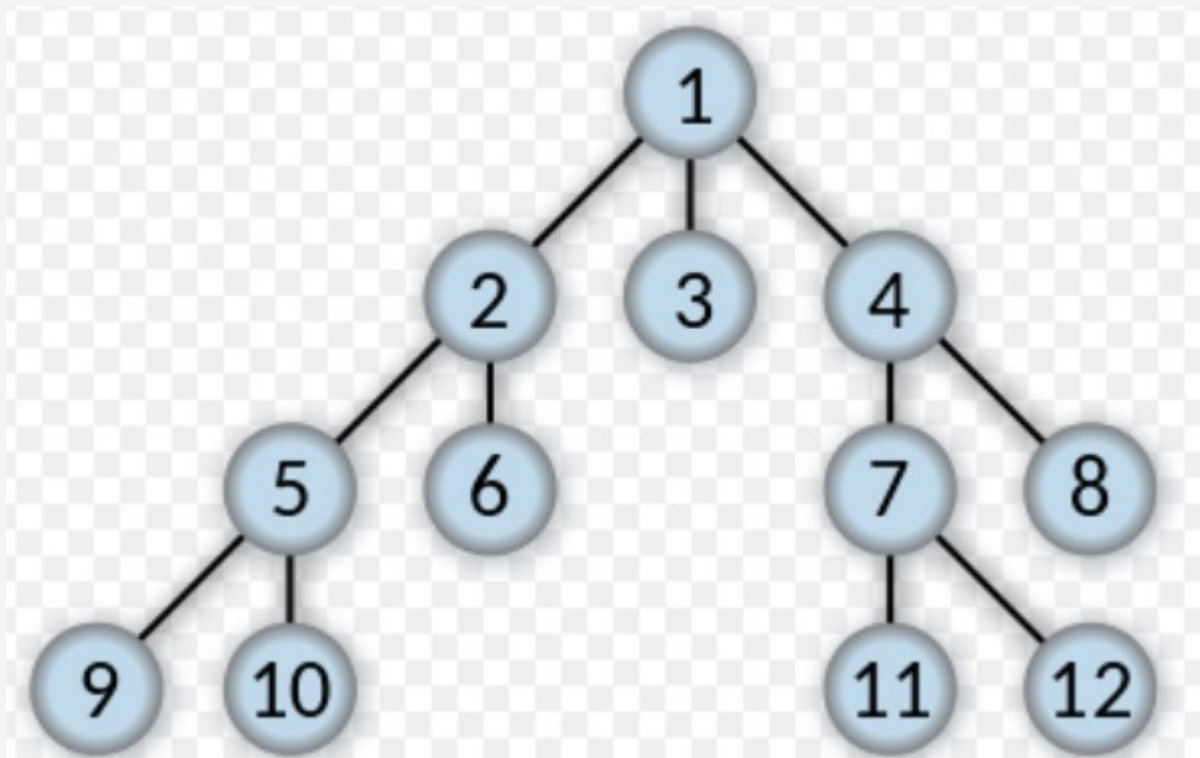
- Some applications require **visiting every vertex** in the graph exactly **once**, in some special **order** based on **graph topology**
- Two orders of graph traversal
 - Breadth-first search (BFS)
 - Depth-first search (DFS)

Breadth-first search (BFS)

- It **starts** at a **root** vertex s , the root at **level 0**
- Visit first the **root** vertex in **level 0**, then vertices in **level 1**, vertices in **level 2**,...
- Level means the **shortest distance** to the **root**
- Need an auxiliary **queue** in the search

BFS example in a tree

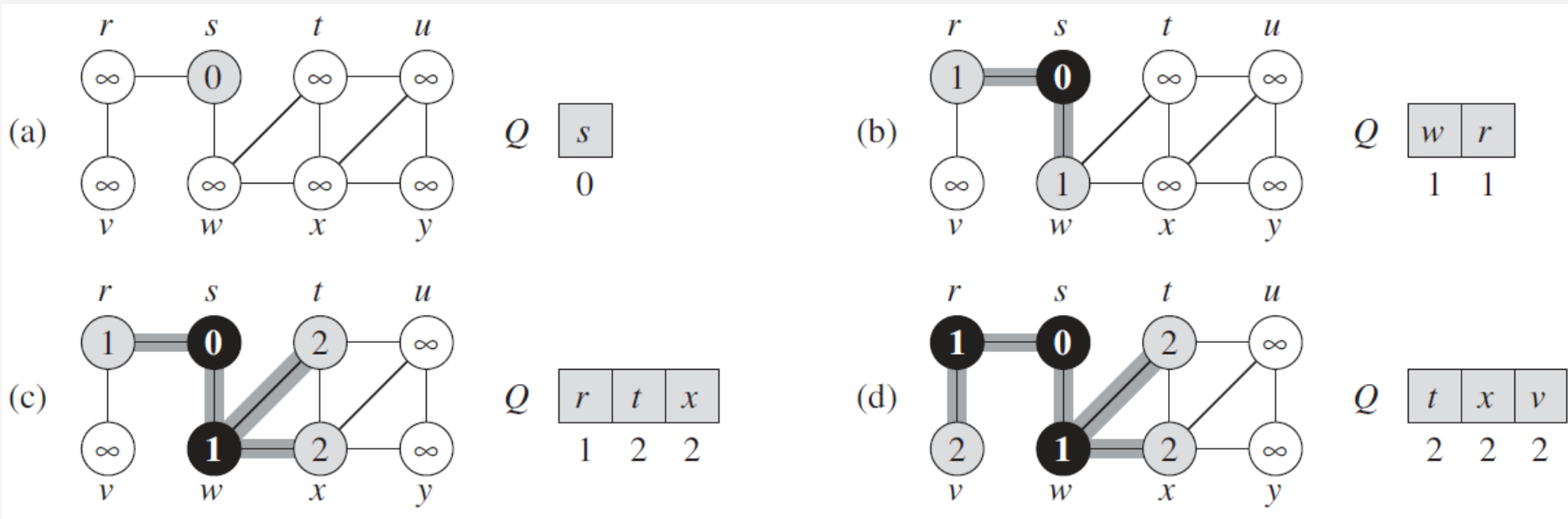
- A tree is a **special** graph
- BFS starts from vertex **1**



Order in which the nodes are visited

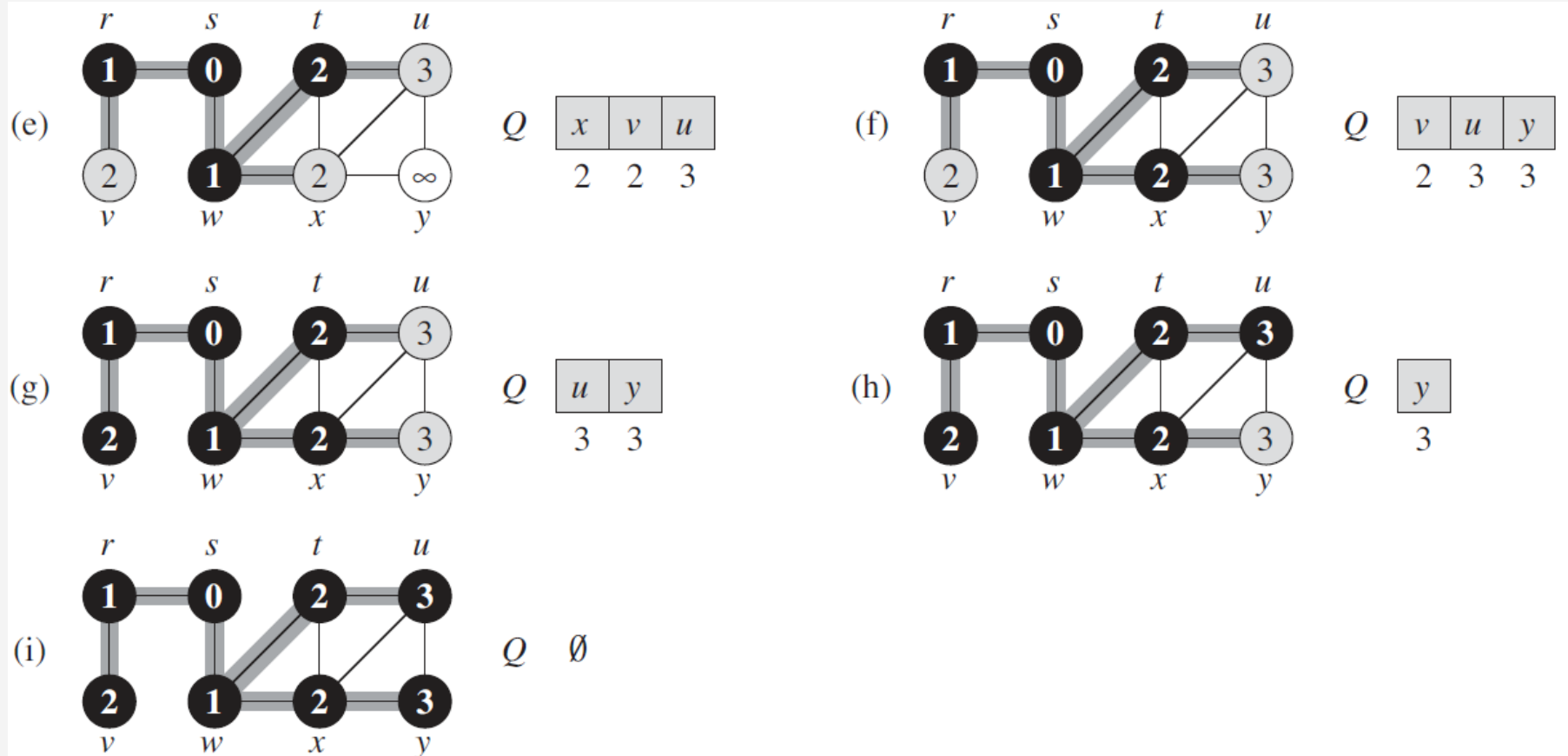
BFS example in a graph, starts from vertex s

- Queue Q stores the **vertices visited**, but has **not** explored their **neighbors**
- Once the **neighbors** of a vertex is **explored**, it is **removed out** from queue Q



BFS example-cont.

- BFS calculates the *shortest distance* of each vertex to **root s** , assume each **edge weight is 1**
- Time complexity of BFS: $\Theta(n+m)$



BFS algorithm

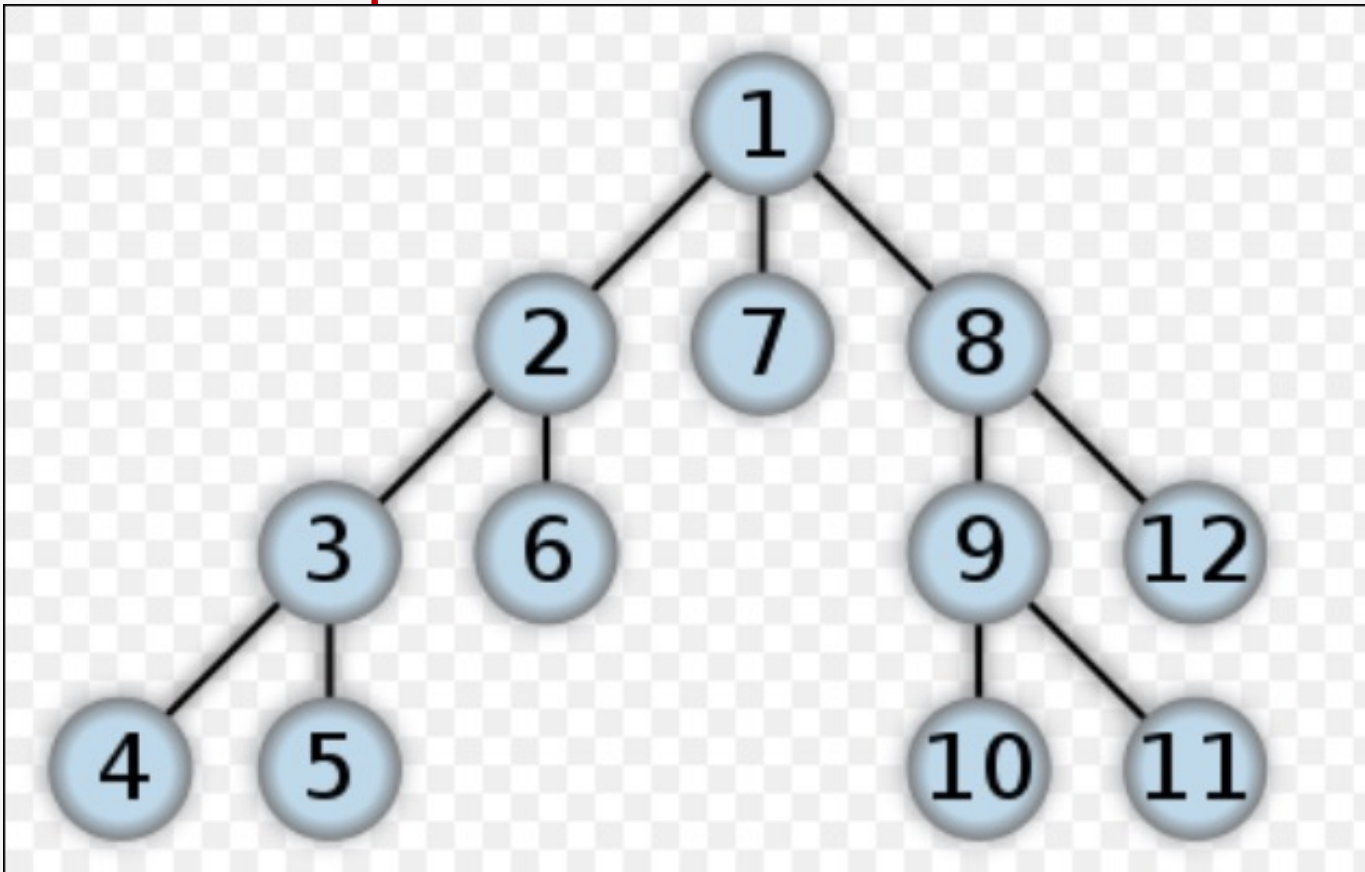
```
void BFS(Graph* G, int s) {
    Queue<int> Q;
    bool *visited = new bool[G->n()];
    for(int i=0; i<G->n(); ++i) visited[i] = false;
    Q->enqueue(s);          // Initialize Q
    visited[s]= true;
    int v, w;
    Node *cur;
    while (Q->length() > 0) { // Process Q
        Q->dequeue(v);
        PreVisit(G, v);    // Take action
        for(cur = G->adjList[v]; cur != NULL; cur=cur->next ) {
            w = cur->nodeID;
            if( false == visited[w] ) {
                visited[w] = true;
                Q->enqueue(w);
            }
        }
    }
    delete []visited;
}
```

Depth-first search (DFS)

- It **starts** at a **root** vertex
- Explore **one branch** of a vertex **as far as possible**, **before** exploring **another branch** of the vertex
- If **no branches** can be explored, **backtrack**

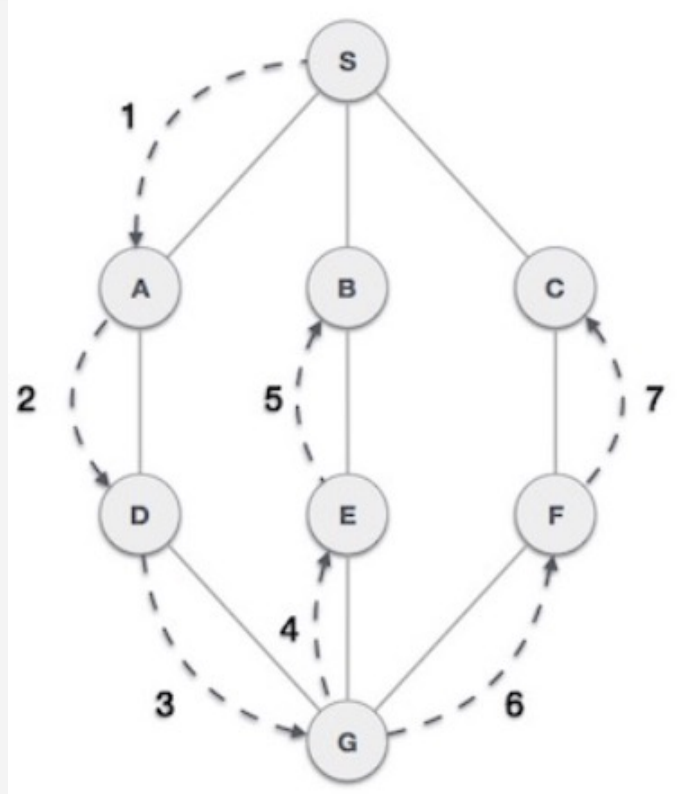
DFS example in a tree

- DFS starts from vertex 1
- Similar to a **pre-order traversal** in a tree



Order in which the nodes are visited

DFS example in a graph, start from vertex **s**



- Vertices are visited in order: **s->A->D->G->E->B->F->C**
- There may be multiple orders
- Another order is: **s->B->E->G->F->C->D->A**

DFS Algorithm

```
void DFS (Graph* G, int v) {
    PreVisit (G, v); // Take action
    visited[ v ] = true;
    Node *cur;
    for ( cur=G->adjList[v]; cur !=NULL;
        cur=cur->next) {
        w = cur->nodeID;
        if ( false == visited[ w ] )
            DFS (G, w );
    }
}
```

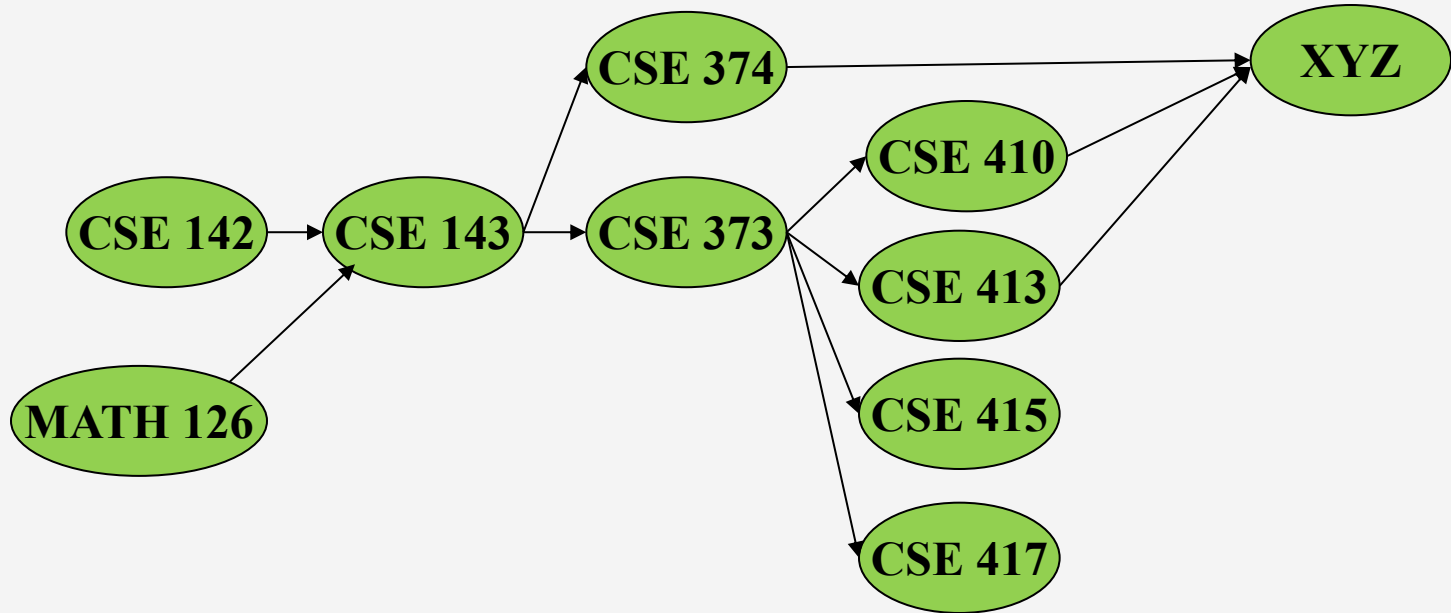
Time complexity: $\Theta(n+m)$

5. Topological Sort, applications:

1. Consider all courses you will learn, some course must be **learned before** another
 - e.g., You must learn **C** before **this course**
 - **List** all courses **in order**, such that **no prerequisite courses** is **after each course** in the order
 - E.g., you cannot learn this course before C
2. Given a set of jobs to be done by a computer, and some jobs must be finished before other jobs
 - **List** all **jobs** in order, such that **no prerequisite jobs** is **after each job** in the order

Topological Sort

- **Problem:** Given a DAG $G = (V, E)$, output all vertices in an order such that no vertex v_j appears before another vertex v_i if there is an edge from v_i to v_j in G

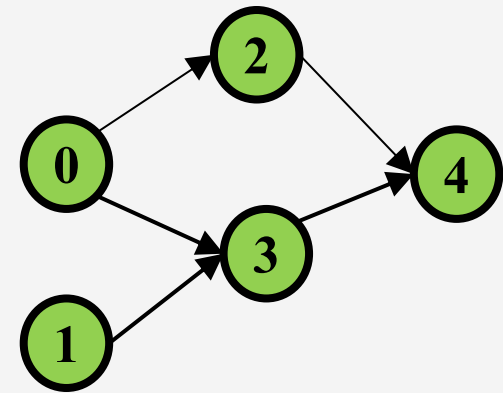


One example output:

126, 142, 143, 374, 373, 417, 410, 413, XYZ, 415

Questions and comments

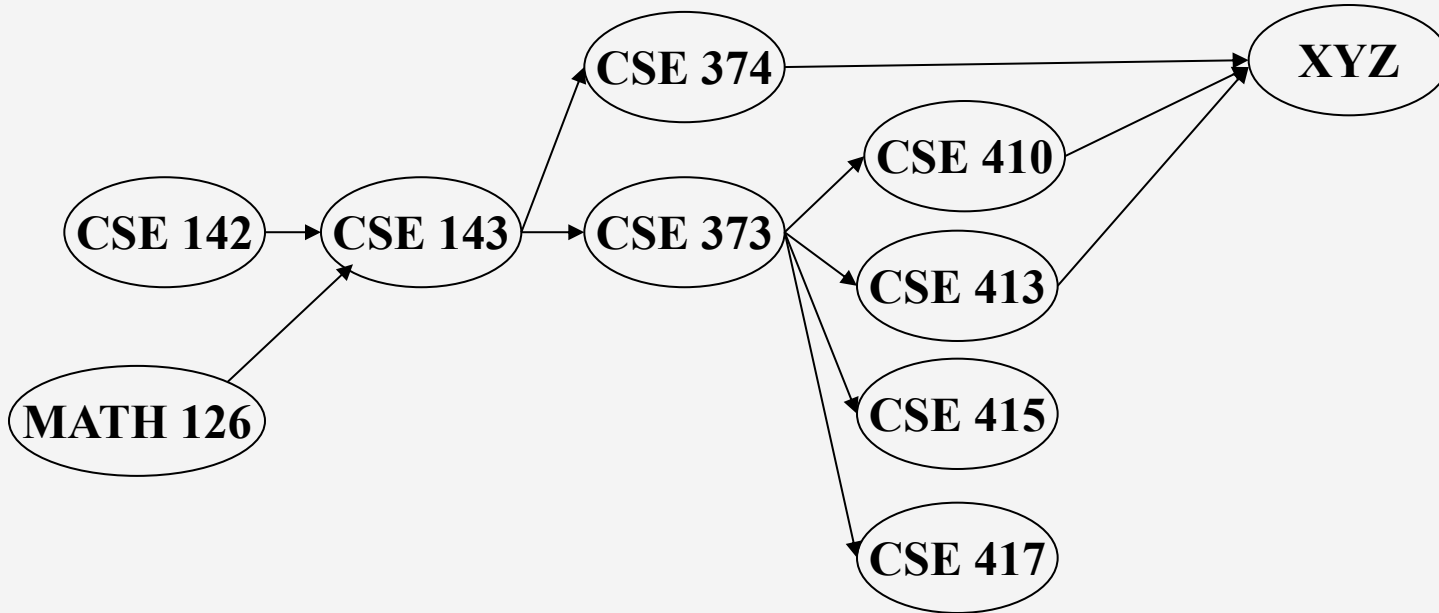
- Why do we perform topological sorts **only on DAGs**?
 - Because a **cycle** means there is **no correct answer**
- Is there always a **unique** order?
 - **No**, there can be **multiple** orders; depends on the graph
- Do some DAGs have exactly 1 order?
 - Yes, e.g., the DAG is a **linked list**



Algorithm for Topological Sort

- While there are vertices not yet output:
 - Choose a vertex v with in-degree of 0, i.e., no dependency
 - Output v and remove it from the graph
 - For each out-going neighbor u of v , decrease the in-degree of u by 1

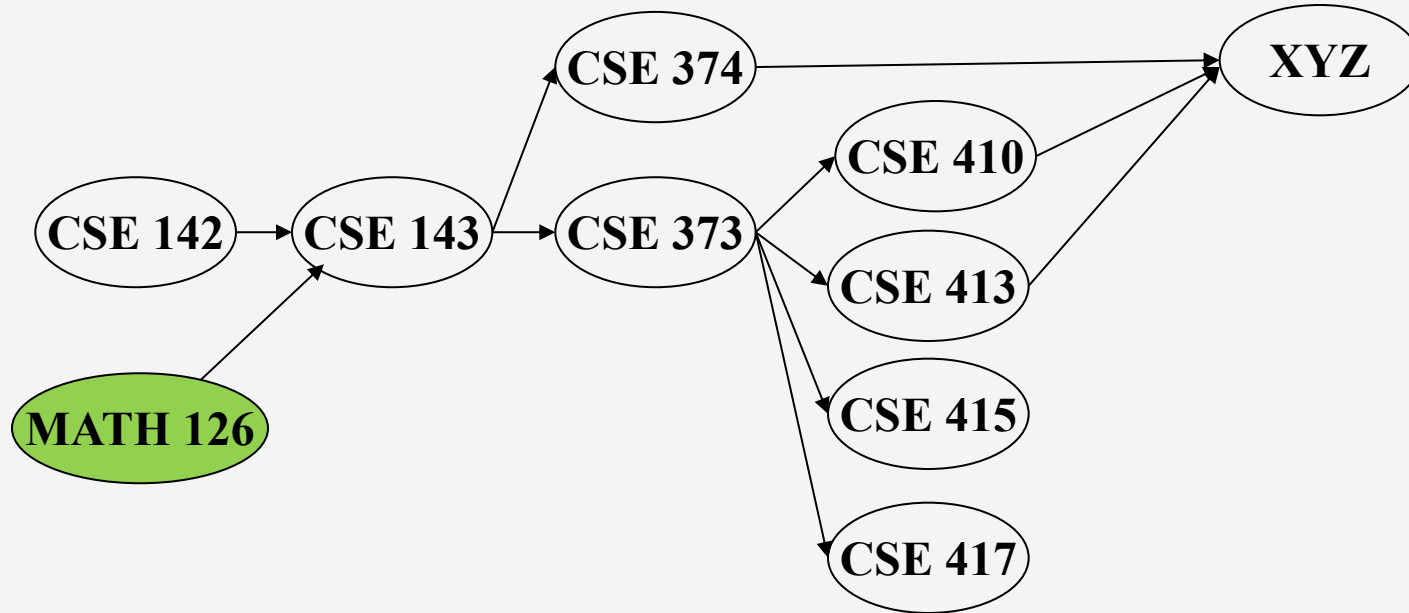
Example



Output:

Node:	126	142	143	374	373	410	413	415	417	XYZ
Removed?										
In-degree:	0	0	2	1	1	1	1	1	1	3

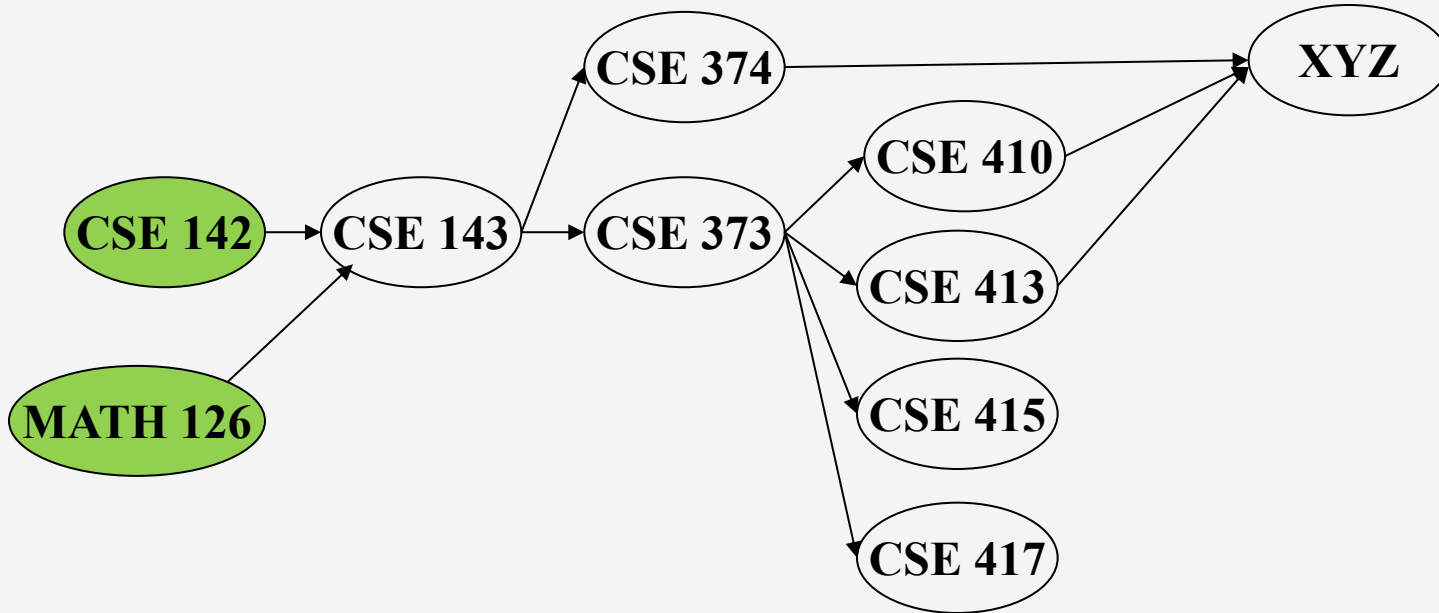
Example



Output:
126

Node:	126	142	143	374	373	410	413	415	417	XYZ
Removed?	x									
In-degree:	0	0	2	1	1	1	1	1	1	3
			1							

Example

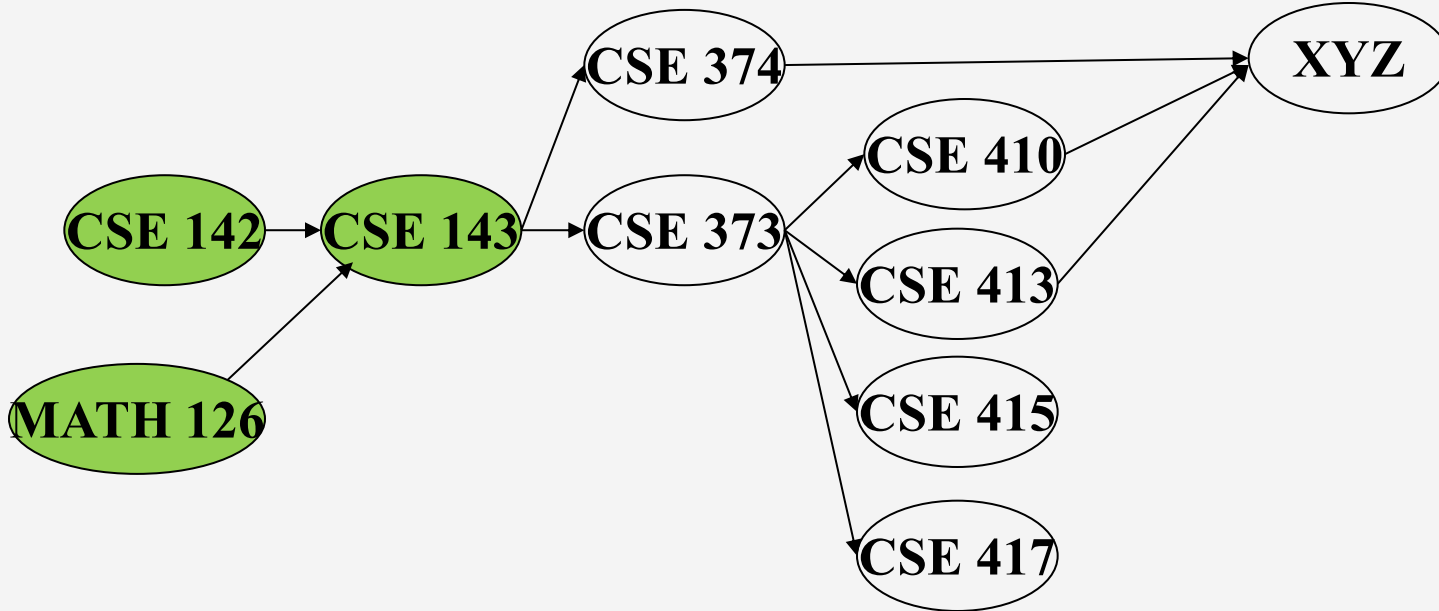


Output:

126
142

Node:	126	142	143	374	373	410	413	415	417	XYZ
Removed?	x	x								
In-degree:	0	0	2	1	1	1	1	1	1	3
			1							
			0							

Example

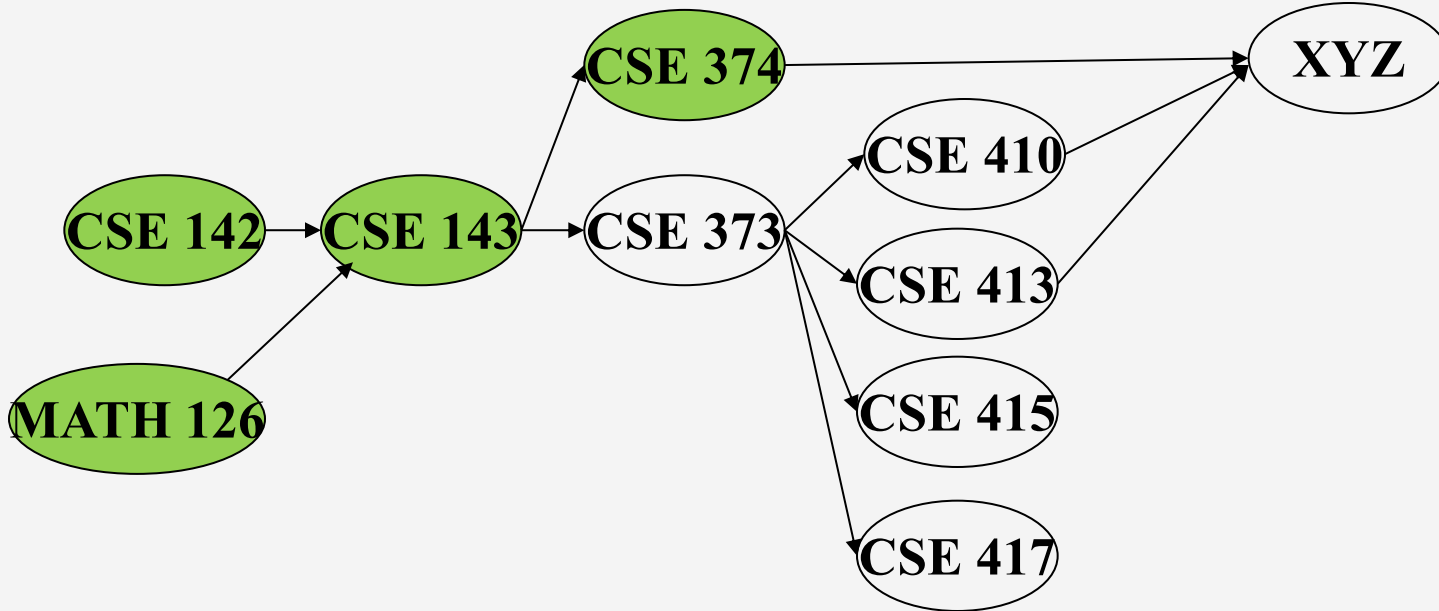


Output:

126
142
143

Node:	126	142	143	374	373	410	413	415	417	XYZ
Removed?		x	x							
In-degree:	0	0	2	1	1	1	1	1	1	3
			1	0	0					
			0							

Example

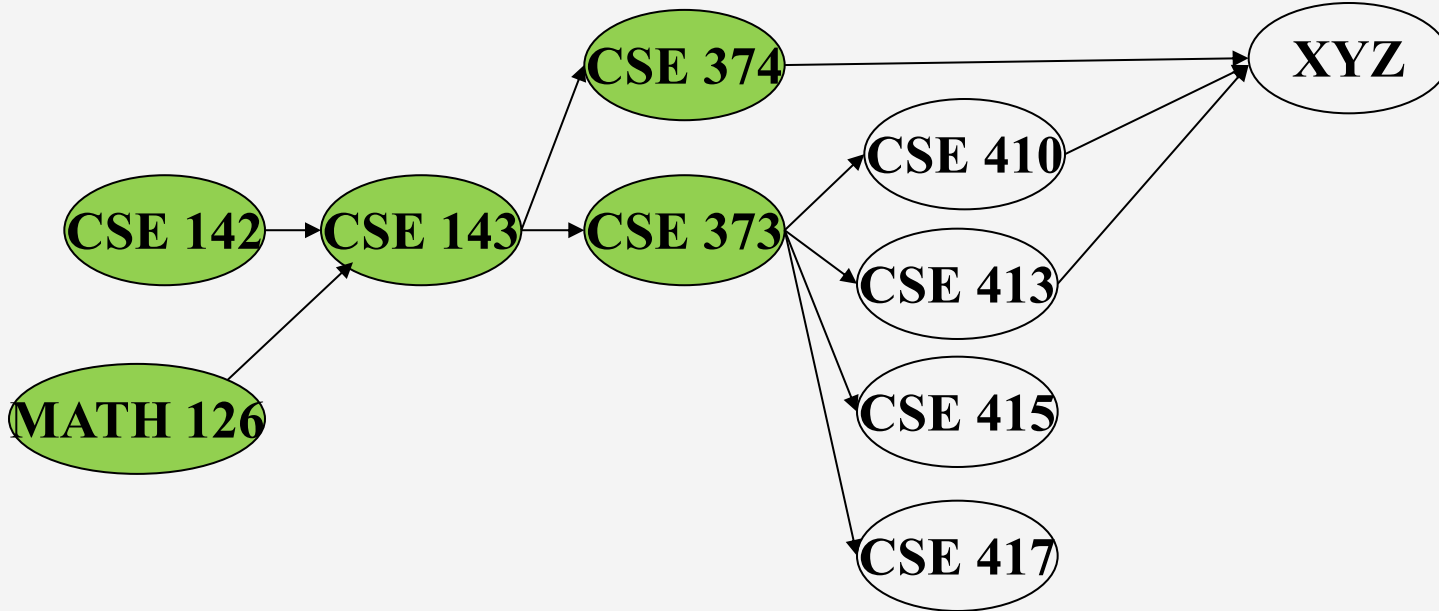


Output:

126
142
143
374

Node:	126	142	143	374	373	410	413	415	417	XYZ
Removed?	x	x	x	x						
In-degree:	0	0	2	1	1	1	1	1	1	3
			1	0	0					2
			0							

Example

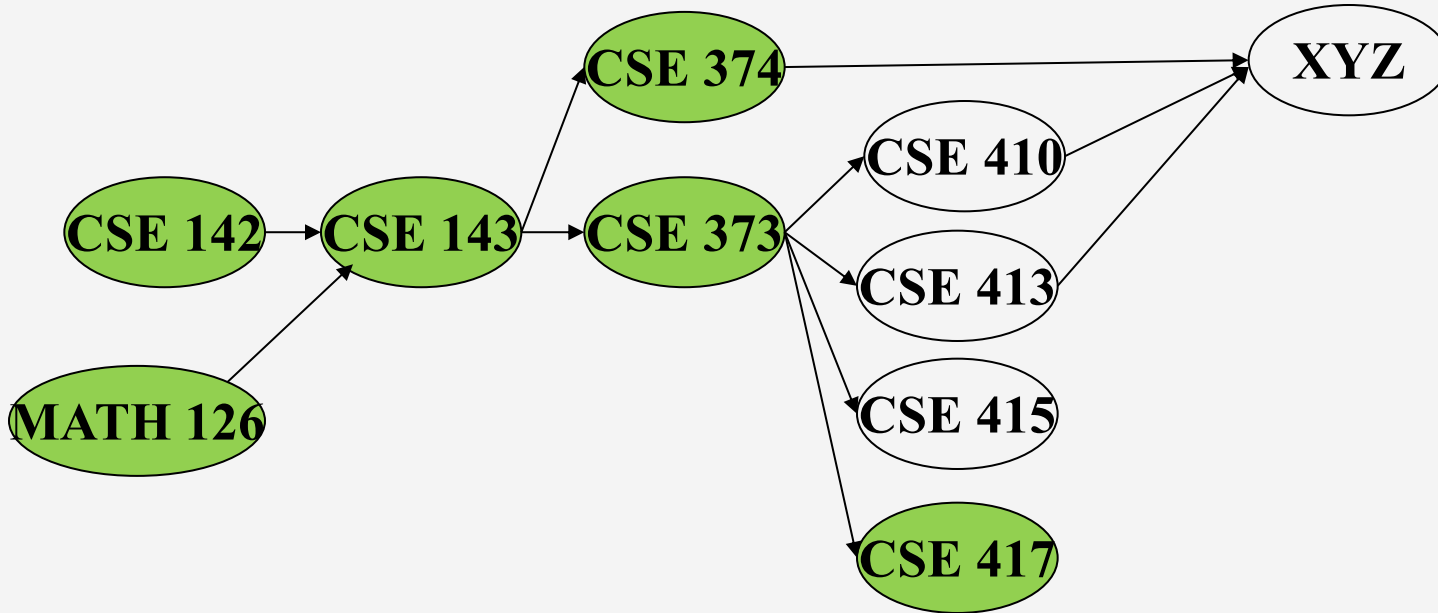


Output:

126
142
143
374
373

Node:	126	142	143	374	373	410	413	415	417	XYZ
Removed?	x	x	x	x	x					
In-degree:	0	0	2	1	1	1	1	1	1	3
			1	0	0	0	0	0	0	2
			0							

Example

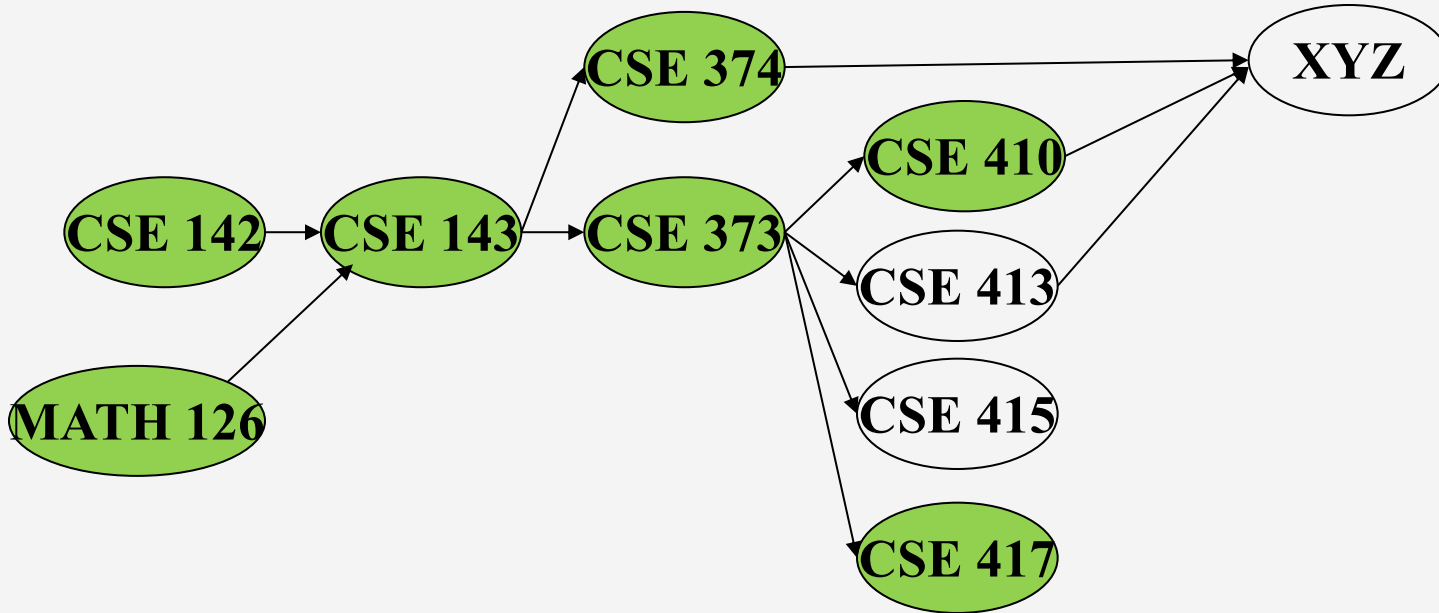


Output:

126
142
143
374
373
417

Node:	126	142	143	374	373	410	413	415	417	XYZ
Removed?	x	x	x	x	x					x
In-degree:	0	0	2	1	1	1	1	1	1	3
			1	0	0	0	0	0	0	2
			0							

Example



Output:

126
142
143
374
373
417
410

Node:	126	142	143	374	373	410	413	415	417	XYZ
Removed?	x	x	x	x	x	x				x
In-degree:	0	0	2	1	1	1	1	1	1	3
			1	0	0	0	0	0	0	2
			0							1

Notice

- Need a vertex with **in-degree 0** to start
 - We can do this because a DAG has **no cycles**
- **Ties** among multiple **vertices** with in-degrees of 0 can be **broken arbitrarily**
- There are **multiple answers** to a topological sort

queue based Topological Sort

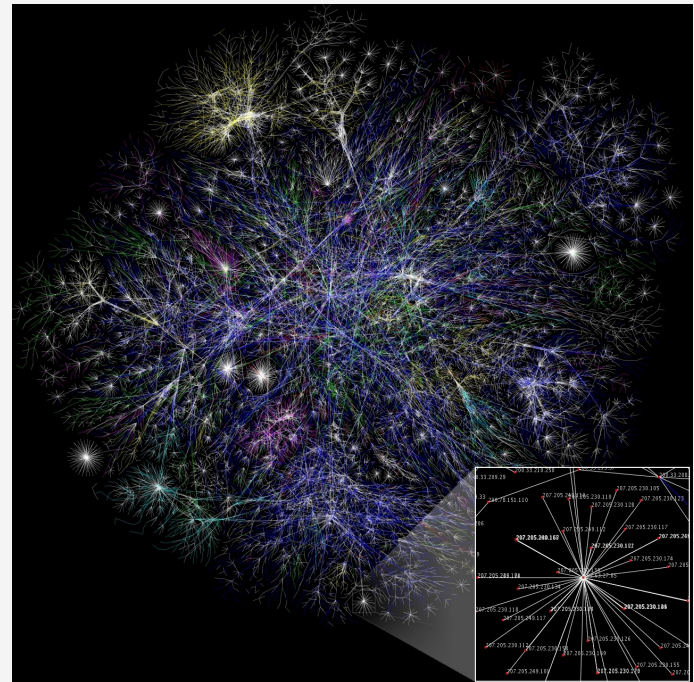
```
void topSort(Graph* G) {
    Queue<int> Q;
    int inDegrees[G->n()];
    int v, w;
    Node *cur;
    for (v=0; v<G->n(); v++) inDegrees[v] = 0;
    for (v=0; v<G->n(); v++) // Process edges
        for (cur=G->adjList[v]; cur!=NULL;
            cur=cur->next ) // out-neighbors of vertex v
            inDegrees[cur->nodeID]++;
    for (v=0; v<G->n(); v++) // Initialize Q
        if (inDegrees[v] == 0) // No in-neighbors
            Q->enqueue(v);
    while (Q->length() > 0) {
        Q->dequeue(v);
        printout(v); // PreVisit for V
        for (cur=G->adjList[v]; cur!=NULL;
            cur=cur->next ) {
            w = cur->nodeID;
            inDegrees[w]--; // One less in-neighb.
            if (inDegrees[w] == 0) // Now free
                Q->enqueue(w);
        }
    }
}
```

Running time

- Initializing queue Q , array inDegrees takes $\Theta(n+m)$
(assuming adjacency list)
- Notice that each vertex enqueues only once , and explore its $\text{out-going neighbors}$ when it dequeues from queue Q
 - Takes time $\Theta(n+m)$
- Total time: $\Theta(n+m)$

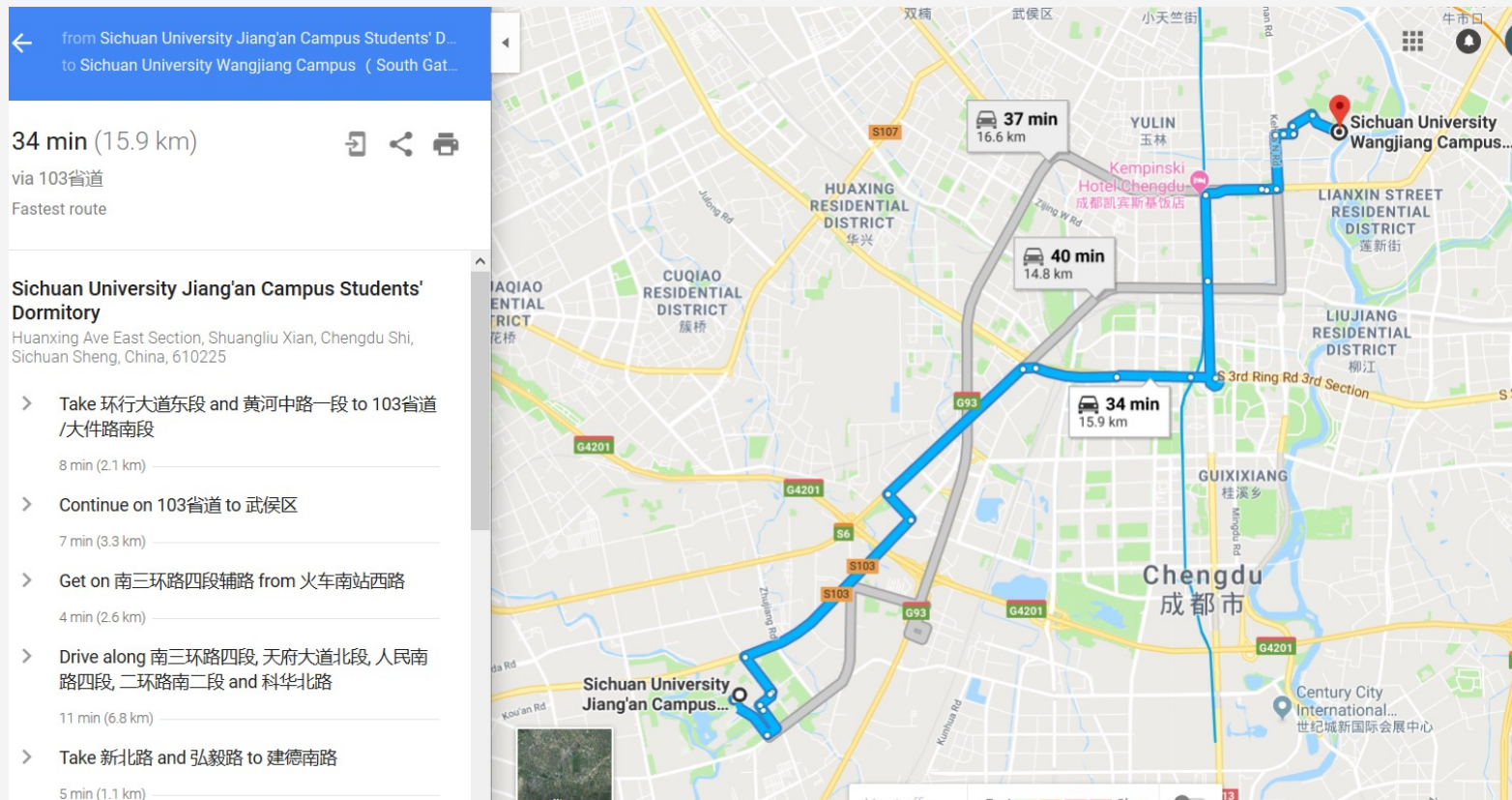
6. Applications of shortest paths

- The Internet is a collection of **interconnected computer networks**
- **Information** is passed from a source **host**, through **routers**, to its destination **server**
- e.g. **a portion of Internet**
- How to **send** the information along **some routers** with **shortest delay**?



Application - google map navigation

- The **driving** path from **Jiang'an campus** to **Wangjiang campus**

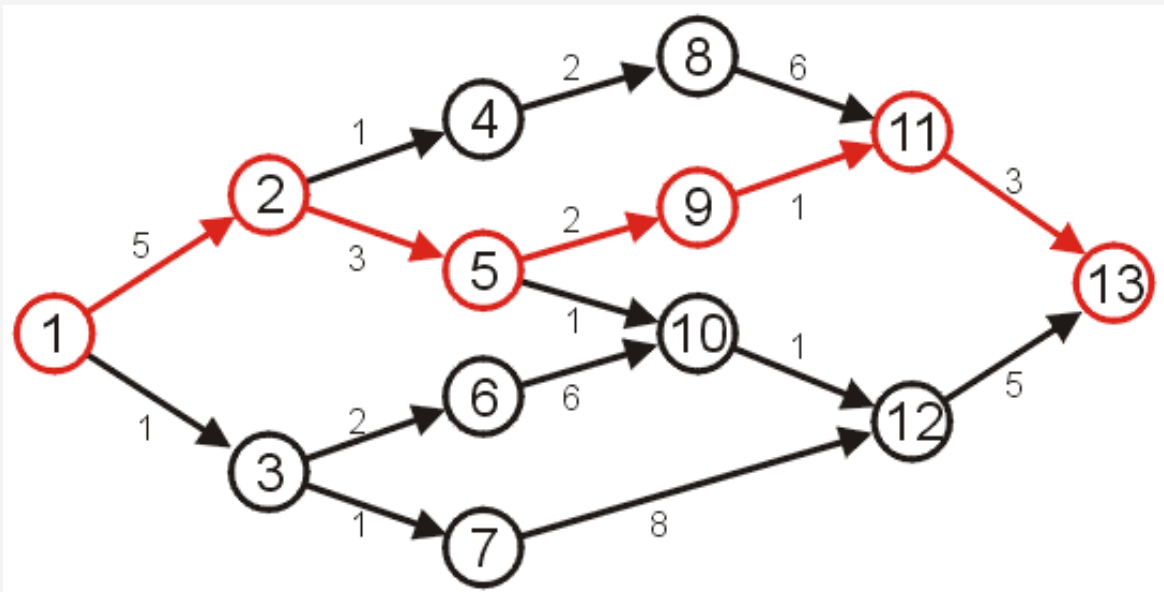


6. Shortest Paths Problems

- **Problem 1:** Given a **weighted** graph, one common problem is to find the **shortest path** from a **source** vertex **s** to a **destination** vertex **t**
- **Problem 2:** find **shortest paths** from a source vertex **s** to all **other vertices**
- The problem 1 is **not easier** than problem 2

Shortest Path

- Find the **shortest path** from vertex **1** to vertex **13**
- Path $1 \rightarrow 2 \rightarrow 5 \rightarrow 9 \rightarrow 11 \rightarrow 13$ is shortest, with **distance 14**
- Other paths are longer, e.g.,
 - path $1 \rightarrow 2 \rightarrow 4 \rightarrow 8 \rightarrow 11 \rightarrow 13$, distance is **17**

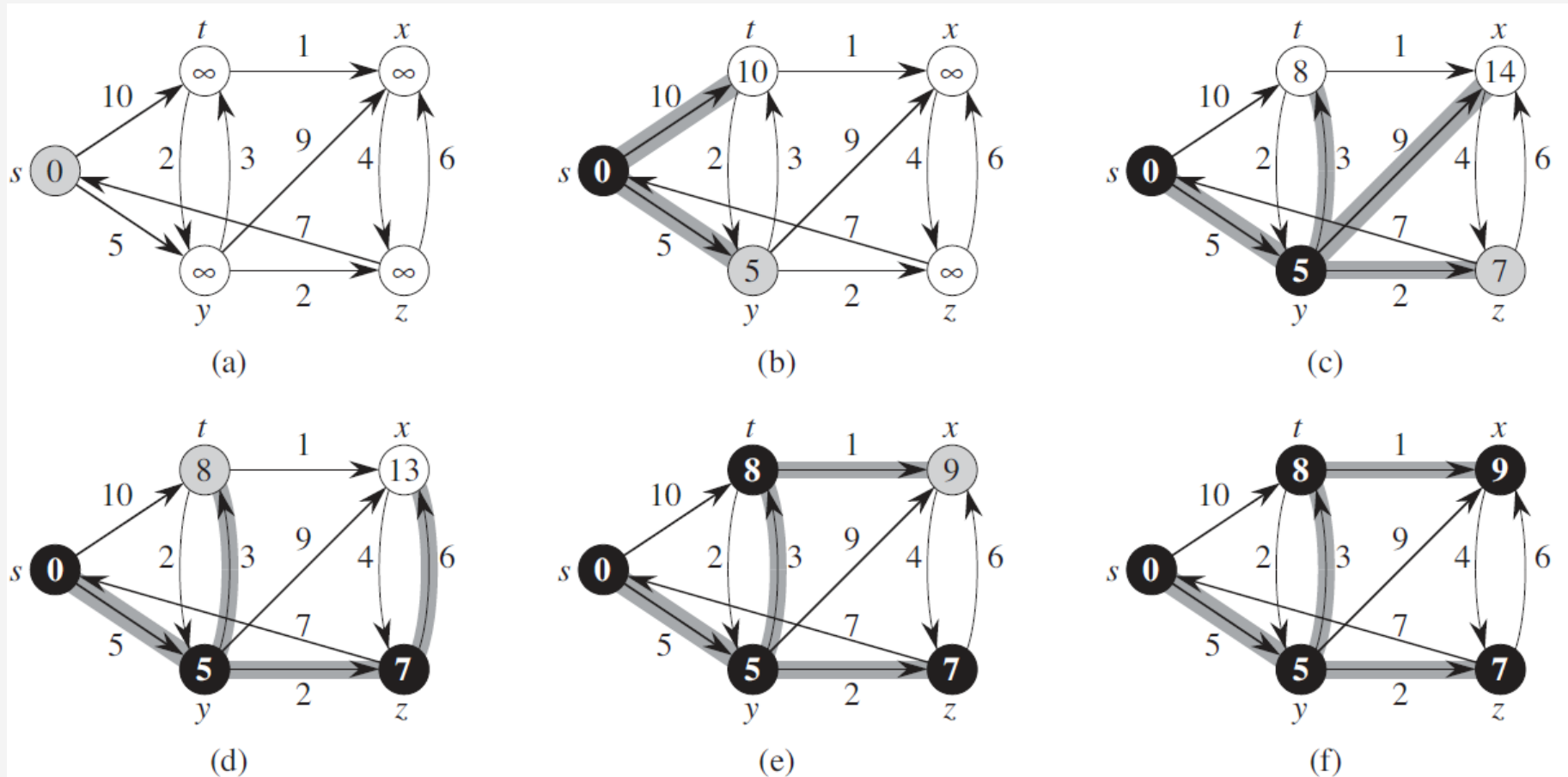


Basic idea of Dijkstra's algorithm

- Find shortest paths from a *source* vertex s to other vertices
- It first *estimates* the *shortest distance* to each vertex
- Assume that we have found the shortest paths from s to a set S of vertices
- It repeatedly selects the vertex u in $V \setminus S$ with the *minimum shortest-path estimate*, adds u to S
- *After* the *adding* of u , *update* the shortest distance *estimates* of vertices *still in* $V \setminus S$

Example of Dijkstra's algorithm

- The value on each vertex is the **shortest distance estimate** or **shortest distance** from s to the vertex

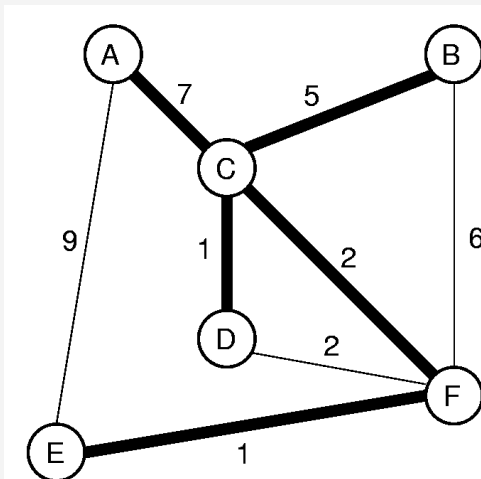


All-Pairs Shortest Paths

- Calculate the shortest paths for all pairs of vertices
- Run Dijkstra's algorithm n times, each time starting from each vertex

7. Minimum Spanning Tree (MST)

- Given an **undirected, connected** graph $G=(V, E)$, and an **edge weight** function: $w: E \rightarrow R$,
- the minimum spanning tree is a **spanning tree** $T=(V, E')$ of G such that the **weighted sum of edges in T** is **minimized**
 - A **spanning tree** $T=(V, E')$ of G is a **subgraph** of G so that the subgraph contains **no cycles** and **spans** vertices in V



Applications of MST

- Direct **applications** in
 - Computer networks
 - telecommunication network
 - transportation networks
 - water supply networks
 - electrical grids
- Invoked as a subroutine for other problems
 - Approximating the travelling salesman problem
 - Steiner tree problem

An application example of MST in telecommunication networks

- A telecommunication company wants to lay cables to a **new neighbourhood** and must **bury cables** along roads. $G=(V, E)$, $w: E \rightarrow R$
 - Each **vertex** is V represents a **building**
 - Each **edge** (u, v) in E represents the **road connects buildings u and v**
 - $w(u,v)$: the **cost** of **burying cables** to connect buildings u and v
- How to **lay cables** to connect the buildings so that the **total cost** is minimized?

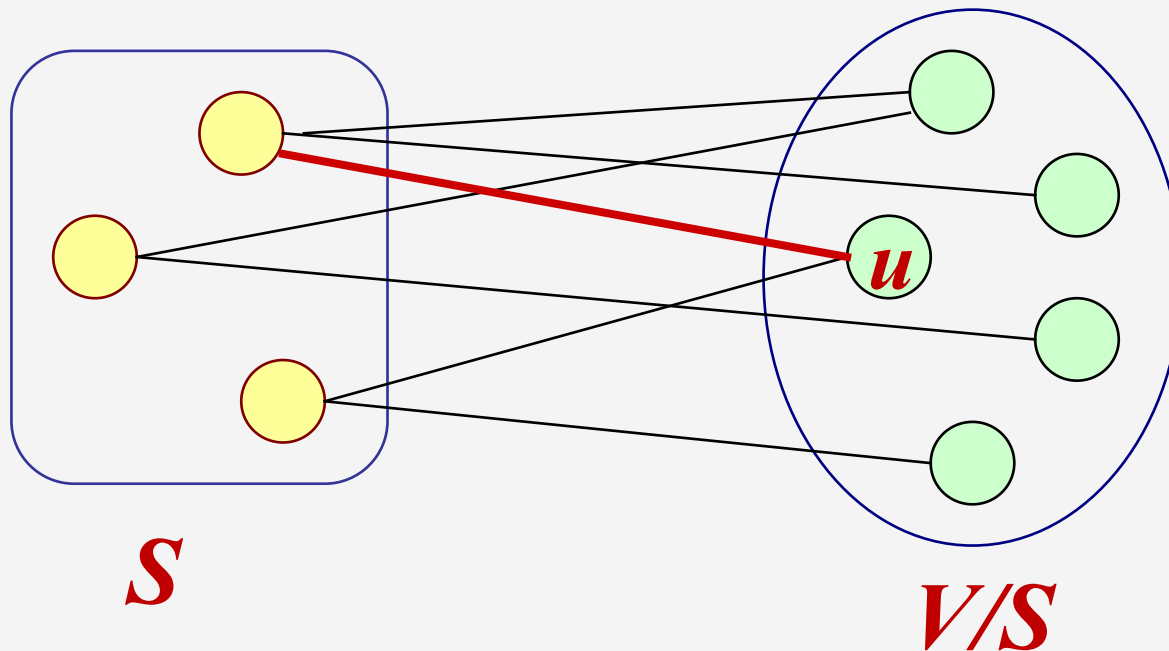


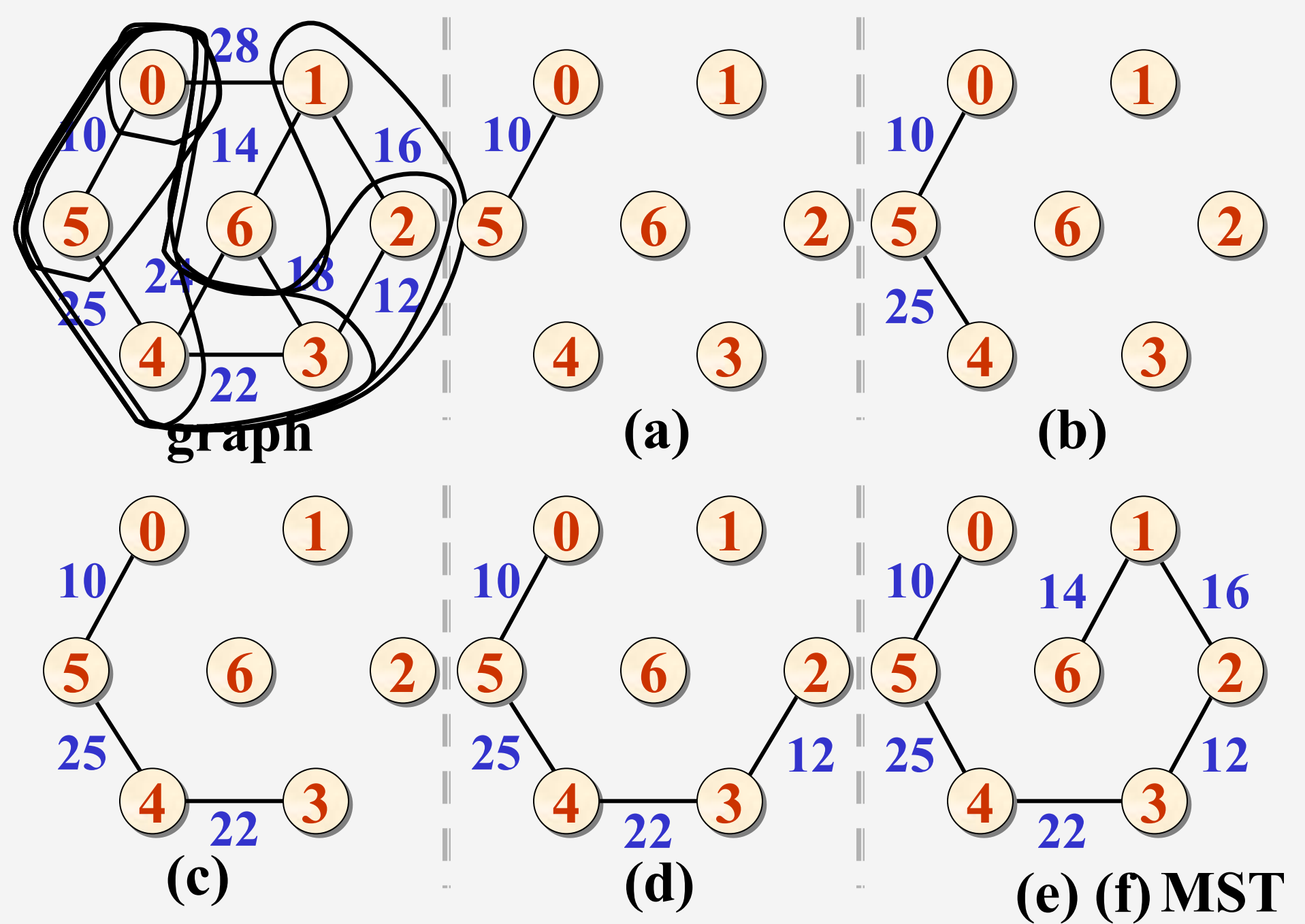
Two **optimal** algorithms to the MST problem

- Kruskal's algorithm
 - $\Theta(n+m \cdot \log n)$
 - $m = |E|, n = |V|$
- Prim's algorithm
 - $\Theta(m + n \cdot \log n)$
- Both construct the MST in a **greedy** way
- Introduce the **Prim's algorithm** as follows, as it is usually **faster** than Kruskal's algorithm

Basic idea of Prim's Algorithm

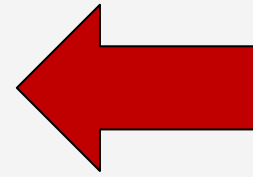
- The MST T grows from **a single vertex**
- Assume that T has already **spanned** some vertices in set S , iteratively **extend** T by removing the **nearest vertex u** in set $V \setminus S$ to S .
- After **$(n-1)$** times of growing, T **spans all nodes** in V





Conclusions

1. Applications of graphs
2. Notations in graphs
3. Graph representations in computers
4. Graph traversals
5. Topological sort
6. Shortest Path
7. Minimum Spanning Tree



**Study Four
common
problems
in graphs**

Homework 4

- See course webpage
- **Deadline:** midnight before next lecture
- Submit to: cs_scu@foxmail.com
- File name format:
 - CS311_Hw4_yourID_yourLastName.doc (or .pdf)